

SVR ENGINEERING COLLEGE
AYYALURUMETTA (V), NANDYAL, KURNOOL
DT.ANDHRA PRADESH – 518502



2021 – 2022

LABORATORY MANUAL

OF

Advanced Data Structures and Algorithms Lab

(20A05301P)

(R-20 REGULATION)

Prepared by

Dr. Rajesh Chandra

ProfessorFor

B.Tech II YEAR – I SEM. (CSE)

**DEPARTMENT OF COMPUTER SCIENCE AND
ENGINEERING**

SVR ENGINEERING COLLEGE

(AFFILIATED TO JNTUA ANANTHAPURAM- AICITE-INDIA)
AYYALURUMETTA (V), NANDYAL, KURNOOL
DT.ANDHRA PRADESH – 518502

LAB MANUAL CONTENT

Advanced Data Structures and Algorithms Lab (20A05301P)

1. Institute Vision & Mission, Department Vision & Mission
2. PO, PEO& PSO Statements.
3. List of Experiments
4. CO-PO Attainment
5. Experiment Code and Outputs

1. Institute Vision & Mission, Department Vision & Mission

Institute Vision:

To produce Competent Engineering Graduates & Managers with a strongbase of Technical & Managerial Knowledge and the Complementary Skills needed to be Successful Professional Engineers & Managers.

Institute Mission:

To fulfill the vision by imparting Quality Technical & Management Education to the Aspiring Students, by creating Effective Teaching/Learning Environment and providing State – of the – Art Infrastructure and Resources.

Department Vision:

To produce Industry ready Software Engineers to meet the challenges of 21st Century.

Department Mission:

- Impart core knowledge and necessary skills in Computer Science and Engineering through innovative teaching and learning methodology.
- Inculcate critical thinking, ethics, lifelong learning and creativity needed for industry and society.
- Cultivate the students with all-round competencies, for career, higher education and self-employability.

2. PO, PEO & PSO Statements

PROGRAMME OUTCOMES (POs)

PO-1: Engineering knowledge - Apply the knowledge of mathematics, science, engineering fundamentals of Computer Science & Engineering to solve complex real-life engineering problems related to CSE.

PO-2: Problem analysis - Identify, formulate, review research literature, and analyze complex engineering problems related to CSE and reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.

PO-3: Design/development of solutions - Design solutions for complex engineering problems related to CSE and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, cultural, societal and environmental considerations.

PO-4: Conduct investigations of complex problems - Use research-based knowledge and research methods, including design of experiments, analysis and interpretation of data and synthesis of the information to provide valid conclusions.

PO-5: Modern tool usage - Select/Create and apply appropriate techniques, resources and modern engineering and IT tools and technologies for rapidly changing computing needs, including prediction and modeling to complex engineering activities, with an understanding of the limitations.

PO-6: The engineer and society - Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the CSE professional engineering practice.

PO-7: Environment and Sustainability - Understand the impact of the CSE professional engineering solutions in societal and environmental contexts and demonstrate the knowledge of, and need for sustainable development.

PO-8: Ethics - Apply ethical principles and commit to professional ethics and responsibilities and norms of the relevant engineering practices.

PO-9: Individual and team work - Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.

PO-10: Communication - Communicate effectively on complex engineering activities with the engineering community and with the society-at-large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, give and receive clear instructions.

PO-11: Project management and finance - Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

PO-12: Life-long learning - Recognize the need for and have the preparation and ability to engage in independent and life-long learning in the broad context of technological changes.

Program Educational Objectives (PEOs):

PEO 1: Graduates will be prepared for analyzing, designing, developing and testing the software solutions and products with creativity and sustainability.

PEO 2: Graduates will be skilled in the use of modern tools for critical problem solving and analyzing industrial and societal requirements.

PEO 3: Graduates will be prepared with managerial and leadership skills for career and starting up own firms.

Program Specific Outcomes (PSOs):

PSO 1: Develop creative solutions by adapting emerging technologies / tools for real time applications.

PSO 2: Apply the acquired knowledge to develop software solutions and innovative mobile apps for various automation applications

2.1 Subject Time Table

SVR ENGINEERING COLLEGE::NANDYAL										
DEPARTMENT OF CSE										
Dr. Rajesh Chandra					II-I					
Day/ Time	9:30 AM	10:20 AM	11:30 AM	12:20 PM-	LUNCH BREAK	02:00 PM	02:50 PM	03:40 PM		
	10:20 AM	11:10AM	12:20 PM	01:10 PM			02:50 PM	03:40 PM	04:30 PM	
MON										
TUE										
WED							ADSA			
THU										
FRI										
SAT										

LIST OF EXPERIMENTS (SYLLABUS)
JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY ANANTAPUR

B.Tech – II-I Sem

(20A05301P) Advanced Data Structures and Algorithms Lab

Course Objectives:

- Learn data structures for various applications.
- Implement different operations of data structures by optimizing the performance.
- Develop applications using Greedy, Divide and Conquer, dynamic programming.
- Implement applications for backtracking algorithms using relevant data structures.

Course Outcomes(CO):

- Understand and apply data structure operations.
- Understand and apply non-linear data structure operations.
- Apply Greedy, divide and conquer algorithms.
- Develop dynamic programming algorithms for various real-time applications.
- Illustrate and apply backtracking algorithms, further able to understand non-deterministic algorithms.

List of Experiments:

1. Write a program to implement the following operations on Binary Search Tree:
a) Insert b) Delete c) Search d) Display
2. Write a program to perform a Binary Search for a given set of integer values.
3. Write a program to implement Splay trees.
4. Write a program to implement Merge sort for the given list of integer values.
5. Write a program to implement Quicksort for the given list of integer values.
6. Write a program to find the solution for the knapsack problem using the greedy method.
7. Write a program to find minimum cost spanning tree using Prim's algorithm
8. Write a program to find minimum cost spanning tree using Kruskal's algorithm
9. Write a program to find a single source shortest path for a given graph.
10. Write a program to find the solution for job sequencing with deadlines problems.

11. Write a program to find the solution for a 0-1 knapsack problem using dynamic programming.
12. Write a program to solve Sum of subsets problem for a given set of distinct numbers using backtracking.
13. Implement NQueen's problem using BackTrackin

1. Write a program to implement the following operations on Binary Search Tree:

- a) Insert b) Delete c) Search d) Display

Binary Search Tree operations in Python

Create a node

class Node:

```
def __init__(self, key):
    self.key = key
    self.left = None
    self.right = None
    # Inorder traversal
def inorder(root):
    If root is not None:
        # Traverse left
        inorder(root.left)
        # Traverse root
        print(str(root.key) + "->", end=' ')
        # Traverse right
        inorder(root.right)
```

Insert a node

```
def insert(node, key):
    # Return a new node if the tree is empty
    if node is None:
        return Node(key)
    # Traverse to the right place and insert the node
    if key < node.key:
        node.left = insert(node.left, key)
    else:
        node.right = insert(node.right, key)
    return node
```

Find the inorder successor

```
def minValueNode(node):
    current = node
    # Find the leftmost leaf
    while(current.left is not None):
        current = current.left
    return current
```

Deleting a node

```
def deleteNode(root, key):
    # Return if the tree is empty
    if root is None:
```

```
        return
        root# Find
```

the node to be deleted

```
if key < root.key:
```

```

        root.left = deleteNode(root.left, key)
    elif(key > root.key):
        root.right = deleteNode(root.right, key)
    else:
        # If the node is with only one child or no child
        if root.left is None:
            temp = root.right
            root = None
            return temp
        elif root.right is None:
            temp = root.left
            root = None
            return temp
        # If the node has two children,
        # place the inorder successor in position of the node to be deleted
        temp = minValueNode(root.right)
        root.key = temp.key
        # Delete the inorder successor
        root.right = deleteNode(root.right, temp.key)
    return root
root = None
root = insert(root, 8)
root = insert(root, 3)
root = insert(root, 1)
root = insert(root, 6)
root = insert(root, 7)
root = insert(root, 10)
root = insert(root, 14)
root = insert(root, 4)
print("Inorder traversal: ", end=' ')
inorder(root)
print("\nDelete 10")
root = deleteNode(root, 10)
print("Inorder traversal: ", end=' ')
inorder(root)

```

OUTPUT

```

Inorder traversal: 1-> 3-> 4-> 6-> 7-> 8-> 10-> 14->
Delete 10
Inorder traversal: 1-> 3-> 4-> 6-> 7-> 8-> 14->

```

```

** Process exited - Return Code: 0 **
Press Enter to exit terminal

```

2. Write a program to perform a Binary Search for a given set of integer values.

Binary Search in python

```
def binarySearch(array, x, low, high):  
    # Repeat until the pointers low and high meet each other  
    while low <= high:  
        mid = low + (high - low)//2  
        if array[mid] == x:  
            return mid  
        elif array[mid] < x:  
            low = mid + 1  
        else:  
            high = mid - 1  
    return -1  
array = [3, 4, 5, 6, 7, 8, 9]  
x = 4  
result = binarySearch(array, x, 0, len(array)-1)  
if result != -1:  
    print("Element is present at index " + str(result))  
else:  
    print("Not found")
```

OUTPUT

Element is present at index 1

** Process exited - Return Code: 0 **

Press Enter to exit terminal

3. Write a program to implement Splay trees.

```
class Node:
    def __init__(self, data):
        self.data = data
        self.parent = None
        self.left = None
        self.right = None

class SplayTree:
    def __init__(self):
        self.root = None

    def maximum(self, x):
        while x.right != None:
            x = x.right
        return x

    def left_rotate(self, x):
        y = x.right
        x.right = y.left
        if y.left != None:
            y.left.parent = x
            y.parent = x.parent
        if x.parent == None: #x is root
            self.root = y
        elif x == x.parent.left: #x is left child
            x.parent.left = y
        else: #x is right child
            x.parent.right = y
            y.left = x
            x.parent = y

    def right_rotate(self, x):
        y = x.left
        x.left = y.right
        if y.right != None:
            y.right.parent = x
            y.parent = x.parent
        if x.parent == None: #x is root
            self.root = y
        elif x == x.parent.right: #x is right child
            x.parent.right = y
        else: #x is left child
            x.parent.left = y
            y.right = x
            x.parent = y

    def splay(self, n):
        while n.parent != None: #node is not root
            if n.parent == self.root: #node is child of root, one rotation
```

```

        if n == n.parent.left:
            self.right_rotate(n.parent)
        else:
            self.left_rotate(n.parent)
        else:
            p = n.parent
            g = p.parent #grandparent
            if n.parent.left == n and p.parent.left == p: #both are left children
                self.right_rotate(g)
                self.right_rotate(p)
            elif n.parent.right == n and p.parent.right == p: #both are right children
                self.left_rotate(g)
                self.left_rotate(p)
            elif n.parent.right == n and p.parent.left == p:
                self.left_rotate(p)
                self.right_rotate(g)
            elif n.parent.left == n and p.parent.right == p:
                self.right_rotate(p)
                self.left_rotate(g)
def insert(self, n):
    y = None
    temp = self.root
    while temp != None:
        y = temp
        if n.data < temp.data:
            temp = temp.left
        else:
            temp = temp.right
            n.parent = y
    if y == None: #newly added node is root
        self.root = n
    elif n.data < y.data:
        y.left = n
    else:
        y.right = n
        self.splay(n)
def search(self, n, x):
    if x == n.data:
        self.splay(n)
        return n
    elif x < n.data:
        return self.search(n.left, x)
    elif x > n.data:
        return self.search(n.right, x)
    else:
        return None

```

```

def delete(self, n):
    self.splay(n)
    left_subtree = SplayTree()
    left_subtree.root = self.root.left
    if left_subtree.root != None:
        left_subtree.root.parent = None
        right_subtree = SplayTree()
        right_subtree.root = self.root.right
    if right_subtree.root != None:
        right_subtree.root.parent = None
    if left_subtree.root != None:
        m = left_subtree.maximum(left_subtree.root)
        left_subtree.splay(m)
        left_subtree.root.right = right_subtree.root
        self.root = left_subtree.root
    else:
        self.root = right_subtree.root
def inorder(self, n):
    if n != None:
        self.inorder(n.left)
        print(n.data)
        self.inorder(n.right)
if __name__ == '__main__':
    t = SplayTree()
    a = Node(10)
    b = Node(20)
    c = Node(30)
    d = Node(100)
    e = Node(90)
    f = Node(40)
    g = Node(50)
    h = Node(60)
    i = Node(70)
    j = Node(80)
    k = Node(150)
    l = Node(110)
    m = Node(120)
    t.insert(a)
    t.insert(b)
    t.insert(c)
    t.insert(d)
    t.insert(e)
    t.insert(f)
    t.insert(g)
    t.insert(h)
    t.insert(i)

```

```
t.insert(j)
t.insert(k)
t.insert(l)
t.insert(m)
t.delete(a)
t.delete(m)
t.inorder(t.root)
```

4. Write a program to implement Merge sort for the given list of integer values.

```
# Python program for implementation of MergeSort
# Merges two subarrays of arr[].
# First subarray is arr[l..m]
# Second subarray is arr[m+1..r]

def merge(arr, l, m, r):
    n1 = m - l + 1
    n2 = r - m
    # create temp arrays
    L = [0] * (n1)
    R = [0] * (n2)
    # Copy data to temp arrays L[] and R[]
    for i in range(0, n1):
        L[i] = arr[l + i]
    for j in range(0, n2):
        R[j] = arr[m + 1 + j]
    # Merge the temp arrays back into arr[l..r]
    i = 0 # Initial index of first subarray
    j = 0 # Initial index of second subarray
    k = l # Initial index of merged subarray
    while i < n1 and j < n2:
        if L[i] <= R[j]:
            arr[k] = L[i]
            i += 1
        else:
            arr[k] = R[j]
            j += 1
        k += 1
    # Copy the remaining elements of L[], if there # are any
    while i < n1:
        arr[k] = L[i]
        i += 1
        k += 1
    # Copy the remaining elements of R[], if there are any
    while j < n2:
        arr[k] = R[j]
        j += 1
        k += 1
    # l is for left index and r is right index of the
    # sub-array of arr to be sorted
def mergeSort(arr, l, r):
```

```
    if l < r:
        # Same as (l+r)//2, but avoids overflow for large l and h
        m = l+(r-l)//2
        # Sort first and second halves
        mergeSort(arr, l, m)
        mergeSort(arr, m+1, r)
        merge(arr, l, m, r)
# Driver code to test above
arr = [12, 11, 13, 5, 6, 7]
n = len(arr)
print("Given array is")
for i in range(n):
    print("%d" % arr[i]),
mergeSort(arr, 0, n-1)
print("\n\nSorted array is")
for i in range(n):
    print("%d" % arr[i]),
```

OUTPUT

```
Given array is
12 11 13 5 6 7

Sorted array is
5 6 7 11 12 13
```

5. Write a program to implement Quick Sort for the given list of integer values.

Python program for implementation of Quicksort Sort

```
def partition(arr, low, high):
    i = (low-1)          # index of smaller element
    pivot = arr[high]   # pivot
    for j in range(low, high):
        # If current element is smaller than or
        # equal to pivot
        if arr[j] <= pivot:
            # increment index of smaller element
            i = i+1
            arr[i], arr[j] = arr[j], arr[i]
    arr[i+1], arr[high] = arr[high], arr[i+1]
    return (i+1)
```

The main function that implements QuickSort

arr[] --> Array to be sorted,

low --> Starting index,

high --> Ending index

Function to do Quick sort

```
def quickSort(arr, low, high):
    if len(arr) == 1:
        return arr
    if low < high:
        # pi is partitioning index, arr[pi] is now
        # at right place
        pi = partition(arr, low, high)
        # Separately sort elements before
        # partition and after partition
        quickSort(arr, low, pi-1)
        quickSort(arr, pi+1, high)
```

Driver code to test above

```
arr = [10, 7, 8, 9, 1, 5]
n = len(arr)
quickSort(arr, 0, n-1)
print("Sorted array is:")
for i in range(n):
    print("%d" % arr[i])
```

OUTPUT

Sorted array is:

1
5
7
8
9
10

**** Process exited - Return Code: 0 ****

Press Enter to exit terminal

6. Write a program to find the solution for the knapsack problem using the greedy method.

```
# Python3 program to solve  
fractional# Knapsack Problem  
class ItemValue:
```

```
    """Item Value DataClass"""  
    def __init__(self, wt, val, ind):  
        self.wt = wt  
        self.val = val  
        self.ind = ind  
        self.cost = val //  
        wt  
  
    def __lt__(self, other):  
        return self.cost < other.cost
```

```
# Greedy Approach  
class FractionalKnapSack:
```

```
    """Time Complexity O(n log  
n)"""  
    @staticmethod  
    def getMaxValue(wt, val, capacity):  
  
        """function to get maximum value"""  
        iVal = []  
        for i in range(len(wt)):  
            iVal.append(ItemValue(wt[i], val[i],  
i))  
  
        # sorting items by value  
        iVal.sort(reverse =  
True)totalValue = 0  
        for i in iVal:  
            curWt = int(i.wt)  
            curVal =  
int(i.val)  
            if capacity - curWt >=  
0:capacity -= curWt  
            totalValue += curVal  
            else:  
                fraction = capacity / curWt  
                totalValue += curVal *  
fraction  
                capacity = int(capacity - (curWt *  
fraction))break
```

```
return totalValue
```

```
# Driver Code
```

```
If __name__ == "_main_":
```

```
    wt = [10, 40, 20, 30]
```

```
    val = [60, 40, 100, 120]
```

```
    capacity = 50
```

```
    maxValue = FractionalKnapSack.getMaxValue(wt, val,  
    capacity)print("Maximum value in Knapsack =", maxValue)
```

OUTPUT:

Maximum value in Knapsack = 240.0

7. Write a program to find minimum cost spanning tree using Prim's Algorithm

```
# Prim's Algorithm in Python

INF = 9999999
# number of vertices in graph N = 5
# creating graph by adjacency matrix method
G = [[0, 19, 5, 0, 0],
      [19, 0, 5, 9, 2],
      [5, 5, 0, 1, 6],
      [0, 9, 1, 0, 1],
      [0, 2, 6, 1, 0]]
selected_node = [0, 0, 0, 0, 0]

no_edge = 0
selected_node[0] = True

# printing for edge and weight
print("Edge : Weight\n")
while (no_edge < N - 1):
    minimum = INF
    a = 0
    b = 0
    for m in range(N):
        if selected_node[m]:
            for n in range(N):
                if ((not selected_node[n]) and G[m][n]):
                    # not in selected and there is an edge
                    if
                        mini
                        mu
                        m >
                        G[m
                        ][n]:
                            mini
                            mu
                            m =
                            G[m
                            ][n]
                            a =
                            m
                            b = n
    print(str(a) + "-" + str(b) + ":" + str(G[a][b]))
    selected_node[b] = True
    no_edge += 1
```

8. Write a program to find minimum cost spanning tree using Kruskal's algorithm.

```
# Python program for Kruskal's algorithm to
find # Minimum Spanning Tree of a given
connected,# undirected and weighted graph
from collections import
defaultdict# Class to represent a
graph
class Graph:
    def __init__(self, vertices):
self.V = vertices # No. of vertices self.graph = [] #
default dictionary# to store graph
    # function to add an edge to
    graphdef addEdge(self, u, v, w):
self.graph.append([u, v, w])
    # A utility function to find set of an
    element i# (uses path compression
    technique)
    def find(self, parent, i):
        if parent[i] == i:
            return i
    return self.find(parent, parent[i])
    # A function that does union of two sets of x
    and y# (uses union by rank)
def union(self, parent, rank, x, y): xroot =
self.find(parent, x)yroot =
self.find(parent, y)
    # Attach smaller rank tree under root of# high rank
    tree (Union by Rank)
        if rank[xroot] < rank[yroot]:
            parent[xroot] = yroot
        elif rank[xroot] >
            rank[yroot]:
            parent[yroot] =
            xroot
    # If ranks are same, then make one as root# and
    increment its rank by one
    else:
        parent[yroot] =
        xrootrank[xroot] +=
```

1

```
# The main function to construct MST using Kruskal's# algorithm
```

```
def KruskalMST(self):  
    result = [] # This will store the resultant MST
```

```

# An index variable, used for sorted edges i = 0
# An index variable, used for result[ ] e = 0
# Step 1: Sort all the edges in
# non-decreasing order of their
# weight. If we are not allowed to change the# given graph,
we can create a copy of graph
self.graph = sorted(self.graph, key=lambda item: item[2])
parent = []
rank = []
# Create V subsets with single elements for node in
range(self.V):
    parent.append(node)
    rank.append(0)
# Number of edges to be taken is equal to V-1 while e < self.V
- 1:
    # Step 2: Pick the smallest edge and
    increment# the index for next iteration
    u, v, w =
    self.graph[i]
    i = i + 1
    x = self.find(parent,
    u)
    y =
    self.find(parent, v)
    # If including this edge doesn't
    # cause cycle, include it in result
    # and increment the index of
    result# for next edge
    if x != y:
        e = e + 1
        result.append([u, v,
        w])
        self.union(parent, rank, x,
        y)
    # Else discard the edge
minimumCost = 0
print ("Edges in the constructed
MST")
for u, v, weight in result:
    minimumCost += weight
    print("%d -- %d == %d" % (u, v,
    weight))
print("Minimum Spanning Tree",
minimumCost)
# Driver
codeg =
Graph(4)
g.addEdge(0, 1, 10)
g.addEdge(0, 2, 6)

```

```
g.addEdge(0, 3, 5)
g.addEdge(1, 3, 15)
g.addEdge(2, 3,
4)# Function call
g.KruskalMST()
```

OUTPUT:

```
Edges in the constructed
MST2 - - 3 = = 4
0 - - 3 = = 5
0 - - 1 = = 10
Minimum Spanning Tree 19
```

9. Write a program to find a single source shortest path for a given graph.

```
import sys
class Graph():
    def __init__(self, vertices):
        self.V = vertices
        self.graph = [[0 for column in range(vertices)]
                      for row in range(vertices)]

    def printSolution(self, dist):
        print "Vertex \tDistance from Source"
        for node in range(self.V):
            print node, "\t", dist[node]

    def minDistance(self, dist, sptSet):
        min = sys.maxint
        for u in range(self.V):
            if dist[u] < min and sptSet[u] == False:
                min = dist[u]
                min_index = u
        return min_index

    def dijkstra(self, src):
        dist = [sys.maxint] * self.V
        dist[src] = 0
        sptSet = [False] * self.V
        for cout in range(self.V):
            x = self.minDistance(dist, sptSet)
            sptSet[x] = True
            for y in range(self.V):
                if self.graph[x][y] > 0 and sptSet[y] == False and \
                    dist[y] > dist[x] + self.graph[x][y]:
                    dist[y] = dist[x] + self.graph[x][y]

        self.printSolution(dist)

g = Graph(9)
g.graph = [[0, 4, 0, 0, 0, 0, 0, 8, 0],
           [4, 0, 8, 0, 0, 0, 0, 11, 0],
           [0, 8, 0, 7, 0, 4, 0, 0, 2],
           [0, 0, 7, 0, 9, 14, 0, 0, 0],
           [0, 0, 0, 9, 0, 10, 0, 0, 0],
           [0, 0, 4, 14, 10, 0, 2, 0, 0],
           [0, 0, 0, 0, 0, 2, 0, 1, 6],
           [8, 11, 0, 0, 0, 0, 1, 0, 7],
           [0, 0, 2, 0, 0, 0, 6, 7, 0]
           ];
g.dijkstra(0);
```

Output:

Vertex Distance from Source

0	0
1	4
2	12
3	19
4	21
5	11
6	9
7	8
8	14

Program 10:**Title:**

Write a program to find the solution for job sequencing with deadlines problems.

Program:

```
def printJobScheduling(arr, t):n =
len(arr)
for i in range(n):
    for j in range(n - 1 - i):
        if arr[j][2] < arr[j + 1][2]:
            arr[j], arr[j + 1] = arr[j + 1], arr[j]
result = [False] * tjob = ['-
1'] * t
for i in range(len(arr)):
    for j in range(min(t - 1, arr[i][1] - 1), -1, -
1):if result[j] is False:
        result[j] = True
        job[j] =
        arr[i][0]break
    print(job)
arr = [['a', 2, 100],
['b', 1, 19],
['c', 2, 27],
['d', 1, 25],
['e', 3, 15]]
print("Following is maximum profit sequence of jobs")
printJobScheduling(arr, 3)
```

OUTPUT:

Following is maximum profit sequence of jobs['c', 'a', 'e']